# **Sperry Marine**



# **NAVIPILOT 4000 Series**



# Self-Tuning Adaptive Heading Control System

# **NAVIPILOT 4000 Series**

# **Ensure Safety and Efficiency**

The highly reliable NAVIPILOT 4000 ensures continuous self-tuning adaptation for accurate steering and efficient fuel consumption, which is unique to all other autopilots in the marine industry.

The NAVIPILOT 4000 Marine Autopilot uses advanced ship steering control network technology to steer a ship safely and efficiently. The innovative NAVIPILOT 4000 is capable of tuning itself to adapt automatically to the ship's load characteristics and weather conditions.

# **Benefits**

- Fully self-tuning adaptive heading control
- Manual selection of steering strategy to suit weather conditions
- Rate and radius control modes
- EC type approved by Germanischer Lloyd, Germany, to MED 96/98/EC (Wheelmark)
- Meets the requirements of all major classification societies
- Ease of use with logical arrangement of sealed foil keyboard

# Configurations

The NAVIPILOT 4000 Series comprises the following system configurations:

- NAVIPILOT 4000 BASIC provides the standard set of system capabilities in accordance with ISO 11674
- NAVIPILOT 4000 TRACK provides additional capabilities for Track Control in accordance with IEC 62065
- NAVIPILOT 4000 HSC provides the capabilities required for High-Speed Craft (HSC) in accordance with ISO 16329
- NAVIPILOT 4000 TRACK HSC provides Track Control capabilities in accordance with IEC 62065 and ISO 16329 for HSC

# **Standard Features**

The following standard features are integrated in all NAVIPILOT 4000 configurations:

- Heading keeping with minimum rudder motion
- Course change control by setting either turn rate or turn radius
- Rudder limit setting (available as an alternative to setting rate or radius)
- Direct RS 422 connection for heading reference or navigation system
- Full alarm complement via the display unit and the alarm contacts

# **Self-Tuning Adaptive Function**

The self-tuning adaptive function is an integral part of all NAVIPILOT 4000 configurations. This feature enables the system to continuously monitor performance and automatically adjust control settings, rudder gain and counter rudder as required to keep the tuning optimized even if the vessel's behaviour is affected by changes in load or trim, or as sea conditions change, to continually provide the best possible steering performance and efficiency.

# **Track Control**

The NAVIPILOT 4000 TRACK and NAVIPILOT 4000 TRACK HSC versions are equipped with the Track Control capability, when interfaced to a Northrop Grumman Sperry Marine Integrated Bridge System or VisionMaster FT ECDIS.

# **High-Speed Craft Features**

The following additional features are provided with NAVIPILOT 4000 High-Speed Craft:

- All standard features
- Fulfills requirements of ISO 16329 for High-Speed Craft
- Jet dead band compensation setting
- Configurable hysteresis setting to provide additional dead zone

## **Ship Automation Features**

- Gyrocompass heading interfaces: two RS 422
- Magnetic compass interfaces: IEC 61162-1, sine/cosine
- Serial interface for track steering via Sperry Marine's VisionMaster FT ECDIS or standard waypoint steering with position receivers
- Additional remote Control and Display Units possible
- Operational data remain stored during power outage
- Clearly arranged graphic liquid crystal display (LCD) with back lighting
- Analogue selection of set heading by means of a cardinal control disk and soft-key selection of all other major parameters
- Analogue output for thruster control, rudder propellers and water jets
- Only serial digital interfaces used

## **Control and Display Unit**

The Control and Display Unit contains a LCD display which permanently indicates the following information:

- Current heading (digital)
- Set heading
- Override status
- Selected heading source
- Steering modes AUTO, NAV or TRACK
- Parameters for
  - Rudder limit or
  - Rate-of-turn or radius (steering mode)
  - Weather
- Preset heading selection
- 1/10° increments of set heading

## Additional Displays

- Load condition
- Speed (auto/man.)
- Rudder order

10

10

- Actual rudder angle or
- Rate of turn
- Cross track error
- Off course alarm
- Heading difference alarm

# Specifications

### Environment

Ambient temperature range Operation Storage Protection grade Installed

Environmental testing To EN 60945 (IEC 945 +A1)

#### Power Requirements

24 VDC (18 V to 36 V) Power consumption Reverse polarity protection

10 W max. Built-in

## Inputs

Rudder angle feedback signal

 $\pm$  10 V ^=  $\pm$  120° max. selectable rudder angle, potentiometer resistance 2 k $\Omega$ 

External steering system

± 10 V ^= ± 120° max. rudder angle

-15° C to +55° C

-25° C to +70° C

IP 32 to DIN 40050

## Flux gate for magnetic compass

Sine/cosine, Sperry Marine product

## NAV/TRACK interface

Serial interface for track steering via VisionMaster FT ECDIS or standard waypoint steering with a position receiver Speed input 200 p/nm or IEC 61162-1 180° turn command Port and starboard

180° turn commandPort ar180° rotation of heading display (for ferries)Gyro / magnetic selectionOverride status

Mute Status signals

AUTO, NFU, Helm, Remote, Ext. System

Set heading and rudder limit or rate or radius control by joystick or pushbutton

Heading

Heading gyro Heading magnetic Two IEC 61162-1 HEHDT at 10 Hz HCHDT or HCHDM or HCHDG at 10 Hz

(solid-state relays)

12 VDC to 110 VDC

(solid-state relays) 24 VAC to 230 VAC

2.0 A max.

1.0 A max.

Optional

Optional

Two for port, two for starboard

Two for port, two for starboard

#### Outputs

## DC solenoid valves

Outputs

Type plus or minus switching Voltage Rating Additional outputs

#### or

### AC solenoid valves

Outputs

Voltage Rating Additional outputs

#### Or Inclate

Isolated proportional analogue output Outputs

Voltage Current Additional outputs Two isolated analogue outputs proportional rudder order to proportional rudder error ±10V DC, max. 20 mA or 4.20 mA Optional

#### Outputs and Interfaces CAN in accordance with IEC 61162-3

for remote control and display units and connection to NAVIGUIDE 4000 manual steering system

# Central alarm IEC

## Voyage Data Recorder (VDR)

Status and alarm outputs System alarm Off course alarm\* Override alarm\* Gyro/Mag. status\* Ext. system status\* Deadman's control\* Mute\* \* max. 4 outputs selectable **Power failure alarm** 

Primary supply Backup supply

#### **Steering Control Unit**

Dimensions Weight Protection grade Magnetic clearance

## Control and Display Unit

Front panel dimensions Installation depth Weight Front panel Display Magnetic clearance 61162-1 bidirectional input/output RS 422 9600 bps

Potential-free contacts 2 A maximum current 250 V maximum voltage

Potential-free contacts A maximum current 250 V maximum voltage

H 151 mm W 392 mm D 425 mm 3 kg IP 32 0.4 m

288 mm x 144 mm to DIN standard 150 mm 1.5 kg Sealed foil keyboard, illuminated Graphic liquid crystal, illuminated 0.4 m



The Royal Carribean cruise ship, the Allure of the Seas, equipped with a NAVIPILOT 4000

# **Sperry Marine**

NORTHROP GRUMMAN

#### BASIC SYSTEM $\leftarrow \Rightarrow$ OPTIONAL EQUIPMENT **Master Unit** Remote Unit 123.4 123.4 123.4 123.4 Steering 159.5 159.5 Mode 144 Selector NAVINET 4000 Steering Control Network • Transmitting NAVIGAT 3000 NAVIGAT X MK 1 Electronic Magnetic Compass with Fluxgate Fiber-Optic Heading Device Gyrocompass Compass Gyrocompass (non-IMO ve (optional) Is only) either-Steering and/or and/or THD and/or or Control Unit Heading: RS 422 and IEC 61162-1 Message IEC 61162-1 sin/cos Magnetic Compass Heading Speed 200 p/nm or IEC 61162-1 NAVITWIN IV Heading Management System with DNV GAS 18 - 36 V DC 18 - 36 V DC Backup Power RS 422 & IEC 61162-1 Messages RS 422 Serial interface for track steering via Rudder Angle Signal Sperry Marine VMS or standard waypoint steering with a position receiver. Universal Digital Repeater Magnetic Heading Central (Fluxgate) **Bidirectional** Alarm Voyage Data Recorder Data Capsule System Steering Rudder Deadman's Analogue Magnetic Gear Angle Contact Compass Repeater Feedback Interface (Fluxgate) Unit

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